## **ELECTRICAL & MECHANICAL ENGINEERING**

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# BMC EXAM GUIDE

Covers Complete Syllabus Of Electrical & Computer Section Only

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Mr. Pramod Deshkari

(20+ Years Teaching Experience)

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- 1. BASICS OF ELECTRICAL ENGINEERING
- 2. ELECTRICAL POWER SYSTEM
- 3. ELECTRICAL & ELECTRONICS MEASUREMENTS
- 4. ELECTRICAL MACHINES

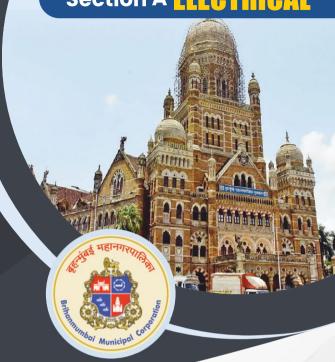
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- 1. INDUSTRIAL AUTOMATION
- 2. INFORMATION COMMUNICATION TECHNOLOGY

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Section A **ELECTRICAL** 



With BMC 2019 Memory Based Questions

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**BMC Sub Engineer & JE EXAM** 

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#### प्रकाशक

Infinity Publications, Pune

पुस्तक मागणीसाठी संपर्क :

8263954946

9607155111

पहिली आवृत्ती : Jan- 2023

द्वितीय आवृत्ती : Aug-2023

अक्षरजुळणी, सजावट व मुखपृष्ठ

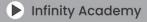
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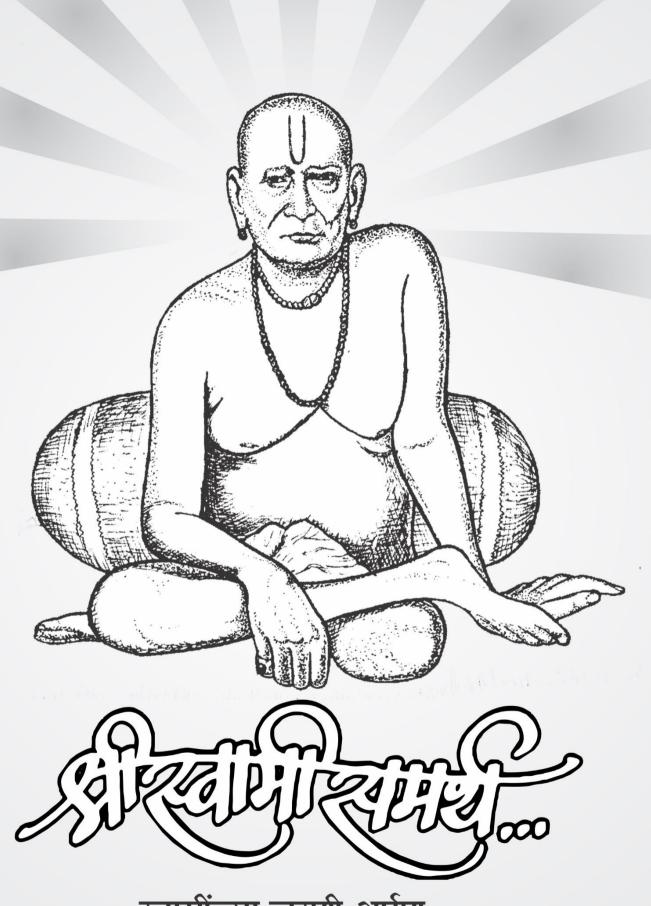
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स्वामींच्या चरणी अर्पण ...

## **PREFACE**

#### Dear Aspirants,

We are extremely happy to present this book for Electrical and Electronics Engineering students those preparing for Bruhan Mumbai Corporation (BMC) Sub-Engineer or Junior Engineer posts and other various competitive examinations.

This book covers Twenty Seven most important topics from various technical subjects including im-portant theory concepts and more than 1500 multiple choice questions. This book includes previous question paper with answer key with practice questions.

Brief review has been added for each topics before taking up the questions. This book includes 2019 BMC memory based question paper with answer key and this book is written considering previous year questions for said examinations.

We tried to represent the concepts in brain mapping format and more in pictorial form and large number of diagrams and illustrations so that the topic understood properly. The topics within the chapters have been arranged in a proper sequence to ensure smooth flow of the subjects.

Topics such as PLC, SCADA and Automation also included in this along with important syllabus topics from computer . Number of MCQs been included so, we are sure that this book will cater all your needs for various examinations.

We are thankful to Infinity Academy and its Publication department for the encouragement and support that they have extended. We are also thankful to Directors and the staff members of Infinity Academy for their efforts to make this book as good as it is. We have jointly made every possible effort to eliminate all the errors in this book. However, if you find any, please let us know, because that will help us to improve further.

P. B. Deshkari

(M.E. (E & TC))

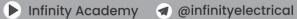
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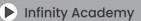




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## ELECTRICAL | MECHANICAL ENGINEERING

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## 1. BASICS OF ELECTRICAL ENGINEERING





### **CHAPTER - 1** INTRODUCTION TO ELECTRICAL ENGINEERING

#### 1.1 Basic concept

#### 1.1.1 Atomic structure

Any substance is made up of matter, matter is made up of tiny particles called atoms and molecules.

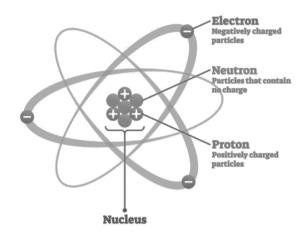


Fig: Atomic structure

- atom can be broken down into three constituents parts - protons, neutron, and electrons.
- Each of these parts has an associated charge, with protons (p) carrying a positive charge, electrons (e-) having a negative charge,
- and neutrons possessing no net charge or electrically neutral
- Electrons are fundamental particles; however, protons and neutrons are made up of a different set of fundamental particles known as quarks.

#### 1.1.2 Charge (q):

- Physical property of matter that causes it to experience a force when placed in an electromagnetic field
- Unit: charge is measured in coulomb (C)
- Electron is negatively charged particles revolving around nucleus in orbits.
- Proton is positively charged particles present in nu-
- Charge on electron =  $-1.6 \times 10^{-19}$  C
- Charge on Proton =  $+ 1.6 \times 10^{-19} \text{ C}$

#### 1.1.3 Electric Current (I)

- Measured in ampere (A)
- Flow of electrons or negatively charged particles in definite direction is current.
- Rate of flow of charge  $I = \frac{dq}{r}$  Or

1 Ampere = 
$$\frac{1Coulomb}{1Second}$$
A  $\longrightarrow$  B +  $\longleftarrow$  q -

- 1 Ampere current: 1 coulomb of charges flows through a conductor in 1 second
- Current is measured by ammeter
- Current is a scalar quantity even it has magnitude and direction because it do not obeys vector laws of addition.
- Electric current has two effect
- 1. Heating effect eg. Application -Water heater
- 2. Magnetic effect eg. Application-Electric Generator

#### 1.1.4 Potential difference:

Amount of work needed to move a charge from a reference point.

Voltage = 
$$\frac{\text{Energ}}{\text{charg}}$$
  
1  $volt = \frac{1 J}{1 C}$ 

It is difference between energy level.

Current only flows from higher potential to lower potential

$$V_A$$
  $\stackrel{R}{\longrightarrow}$   $V_B$ 

- V<sub>A</sub> > V<sub>B</sub> then current flows from terminal A to B.
- Potential difference is =  $V_A V_B$
- Voltage drop across R is =  $\frac{VA VB}{R}$

potential difference is measured in volts (V)

- 1 volt potential difference A voltage difference of one volt drives one ampere of current through a conductor that has a resistance of one ohm. Or
- One joule of work is required to move an electric charge of one coulomb across a potential difference of one volt. Or
- One volt is equivalent to one joule per coulomb.



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### **IMPORTANT QUESTIONS**

## Part - 1

#### 1. Basic source of magnetism

- A. Charged particles alone
- B. Movement of charged particles
- C. Magnetic dipoles
- D. Magnetic domains

1. Answer: B

#### 2. Units for magnetic flux density

- A. Wb  $/ m^2$
- B. Wb/A.m
- C. A / m
- D. Tesla / m

2. Answer: A

#### 3. Magnetic permeability has units as

- A. Wb / m2
- B. Wb / A.m
- C. A / m
- D. Tesla / m

3. Answer: B

#### 4. Magnetic permeability has units as

- A. Tesla
- B. Henry
- C. Tesla/m
- D. Henry/m

4. Answer: D

#### 5. Magnetic field strength's units are

- A. Wb/m2
- B. Wb/A.m
- C. A/m
- D. Tesla/m

5. Answer: C

#### 6. Example for dia-magnetic materials

- A. Super conductors B.
- Alkali metals
- C. Transition metals D.
  - D. Ferrites

6. Answer: A

#### 7. Example for para-magnetic materials

- A. Super conductors B.
- Alkali metals
- C. Transition metals D.
- D. Ferrites

7. Answer: B

#### 8. Example for ferro-magnetic materials

- A. Super conductors B.
- Alkali metals
- C. Transition metals D.
- Ferrites

8. Answer: C

#### 9. Example for anti-ferro-magnetic materials

- A. Salts of transition elements
- B. Rare earth elements
- C. Transition metals
- D. Ferrites

9. Answer: A

#### 10. Example for ferri-magnetic materials

A. Salts of transition elements

- B. Rare earth elements
- C. Transition metals
- D. Ferrite

10. Answer: D

## 11. Which of following circuit element stores energy in electromagnetic field?

- A. Inductor
- B. Condenser
- C. Variable resistor
- D. Capacitor

11. Answer: A

#### 12. Emf induced in a coil rotating in a uniform magnetic field will be maximum when the

- A. Flux linking with the coil is maximum
- B. Rate of change of flux linkage is minimum.
- C. Rate of change of flux linkage is maximum.
- D. Rate of cutting flux by coil sides is minimum.

12. Answer: C

## 13. The emf induced in a conductor rotating in bipolar field is

- A. Dc
- B. Ac
- C. Dc and ac both
- D. None of these

13. Answer: B

#### 14. The direction of induced emf can be found by

- A. Kirchhoff's law
- B. Lenz law
- C. Fleming's right hand rule
- D. Laplace law

14. Answer: C

## 15. A coil with negligible resistance has 50 V across it with 10 mA. The inductive reactance is

- A. 50ohms
- B. 500ohms
- C. 1000ohms
- D. 5000ohms

15. Answer: D

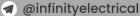
#### 16. A copper disc is rotated rapidly below a freely suspended magnetic needle. The magnetic needle starts rotating with velocity

- Equal to that of disc and in the same direction.
- B. Equal to that of disc and in the opposite di-
- Less than that of disc and in the same direction.
- Less than that of disc but in opposite direction.











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**4. Electrical Machines** 



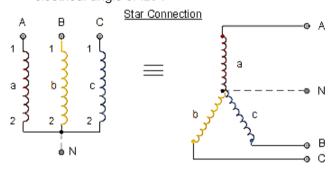


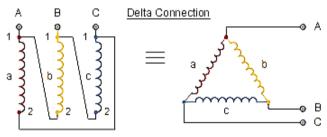
### CHAPTER – 1 THREE PHASE INDUCTION MOTOR

#### Introduction

#### **Production of rotating MMF**

The stator of an induction motor consists of a number of overlapping windings balanced by an electrical angle of 120°.

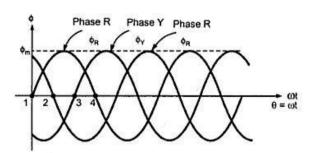


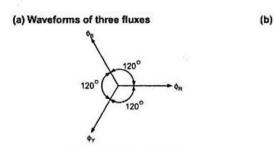


- When the stator is connected to a three-phase alternating current supply, it establishes a rotating magnetic field which rotates at a synchronous speed.
- The magnitude of this rotating field is constant and is equal to 1.5 times maximum magnitude of flux:

$$\emptyset(\theta, t) = 1.5\emptyset_m$$

- A three-phase induction motor consists of three phase winding (star or delta) as its stationary part called stator.
- The three phase currents flow simultaneously through the windings and are displaced from each other by 120° electrical.
- Each alternating phase current produces sinusoidal flux. So, all three fluxes are sinusoidal and are separated from each other by 120°.





Assumed positive directions

If the phase sequence of the windings is R-Y-B, then mathematical equations for the instantaneous values of the three fluxes  $\emptyset_R$ ,  $\emptyset_B$ ,  $\emptyset_Y$  can be written as,

$$\emptyset_R = \emptyset_m \sin(\omega t) 
\emptyset_R = \emptyset_m \sin(\omega t - 120)$$

$$\emptyset_Y = \emptyset_m \sin(\omega t - 240)$$

- As windings are identical and supply is balanced, the magnitude of each flux is  $\emptyset_m$ .
- The waveform of the three fluxes is as given below:

#### **Construction of Stator**

- A three phase Induction motor mainly consists of two parts called as the Stator and the Rotor.
- The stator is the stationary part of the induction motor, and the rotor is the rotating part.

#### 1. Stator:

- It is built up of high-grade alloy steel laminations to reduce eddy current losses.
- It has three main parts, namely outer frame, the stator core and a stator winding.

#### 2. Outer frame

It is the outer body of the motor to support the stator core and to protect the inner parts of the machine.





# ELECTRICAL & MECHANICAL ENGINEERING

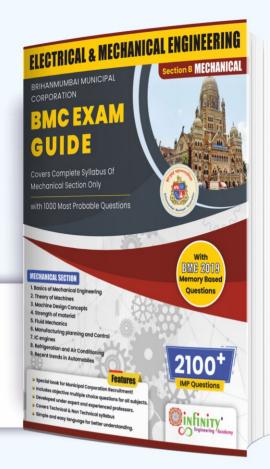
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- 3. Machine Design Concepts
- 4. Strength of material
- 5. Fluid Mechanics
- 6. Manufacturing planning and Control
- 7. IC engines
- 8. Refrigeration and Air Conditioning
- 9. Recent trends in Automobiles



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